

A further asymptotic behavior result on certain non-autonomous differential equations of fifth order

Cemil Tunç

Department of Mathematics, Faculty of Arts and Sciences,

Yüzüncü Yıl University,

65080, Van- Turkey.

E-mail: cemtunc@yahoo.com

Abstract

In the current paper, we present some sufficient conditions under which all solutions of a certain fifth order differential equation are uniformly bounded and tend to zero together with their derivatives of the fourth order as $t \rightarrow \infty$. Our result includes and improves some well-known results in the literature ([2], [3], [15]).

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1. Introduction

We are interested in obtaining a result on the asymptotic behaviour of solutions of the fifth order differential equations of the form

$$\begin{aligned} x^{(5)} + f_1(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)})x^{(4)} + b(t)f_2(x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}) + c(t)f_3(x, \dot{x}, \ddot{x}) \\ + d(t)f_4(x, \dot{x}) + e(t)f_5(x) = p(t, x, \dot{x}, \ddot{x}, \ddot{\ddot{x}}, x^{(4)}) \end{aligned} \quad (1.1)$$

or its equivalent system

$$\begin{aligned} \dot{x} &= y \\ \dot{y} &= z \\ \dot{z} &= w \\ \dot{w} &= u \\ \dot{u} &= -f_1(t, x, y, z, w, u)u - b(t)f_2(x, y, z, w) - c(t)f_3(x, y, z) \\ &\quad - d(t)f_4(x, y) - e(t)f_5(x) + p(t, x, y, z, w, u), \end{aligned} \quad (1.2)$$

where $b, \dots, e, f_1, \dots, f_5$ and p are continuous functions for the arguments displayed explicitly in (1.2). It is assumed that the functions b, \dots, e are positive definite and differentiable in $R^+ = [0, \infty)$ and the derivatives $\frac{\partial}{\partial x} f_2(x, y, z, w)$, $\frac{\partial}{\partial y} f_2(x, y, z, w)$, $\frac{\partial}{\partial z} f_2(x, y, z, w)$, $\frac{\partial}{\partial x} f_3(x, y, z)$, $\frac{\partial}{\partial y} f_3(x, y, z)$, $\frac{\partial}{\partial x} f_4(x, y)$, $\frac{\partial}{\partial y} f_4(x, y)$ and $f_5'(x)$ exist and are continuous for all x, y, z and w . All solutions considered are also assumed to be real valued.

In recent years, the qualitative behavior of solutions for various classes of certain fifth order non-linear differential equations have been widely discussed in the literature (see, for example, Abou-El-Ela and Sadek [1], Adesina [4], Chukwu ([5], [6]), Tunç ([12], [13], [14], [18]) and Yuan-hong [19] and the references quoted therein). In general, the investigators have given sufficient conditions for stability and boundedness of solutions. However, according to our observations in the relevant literature, only a few researches have been carried out on the asymptotic behavior of solutions of certain fifth-order ordinary differential equations such as Abou-El-Ela and Sadek ([2], [3]), Sadek [11] and Tunç ([15], [17], [18]). More recently, the authors in ([2], [3]) and ([15], [17]) discussed the same subject for the differential equation (1.1) and the equations as follows:

$$\begin{aligned} x^{(5)} + a(t)f_1(\ddot{x}, \ddot{x})x^{(4)} + b(t)f_2(\ddot{x}, \ddot{x}) + c(t)f_3(\ddot{x}) + d(t)f_4(\dot{x}) + e(t)f_5(x) \\ = p(t, x, \dot{x}, \ddot{x}, \ddot{x}, x^{(4)}) \end{aligned}$$

and

$$\begin{aligned} x^{(5)} + f_1(t, x, \dot{x}, \ddot{x}, \ddot{x}, x^{(4)})x^{(4)} + b(t)f_2(\ddot{x}, \ddot{x}) + c(t)f_3(\dot{x}, \ddot{x}) + d(t)f_4(\dot{x}) + e(t)f_5(x) \\ = p(t, x, \dot{x}, \ddot{x}, \ddot{x}, x^{(4)}), \end{aligned}$$

$$\begin{aligned} x^{(5)} + f_1(t, x, \dot{x}, \ddot{x}, \ddot{x}, x^{(4)})x^{(4)} + \phi(t, \ddot{x}, \ddot{x}) + \psi(t, \dot{x}, \ddot{x}) + g(t, x, \dot{x}) + e(t)h(x) \\ = p(t, x, \dot{x}, \ddot{x}, \ddot{x}, x^{(4)}), \end{aligned}$$

respectively.

The motivation for the present work, especially, has come from the papers of Abou-El-Ela and Sadek ([2], [3]), Hara ([7], [8], [9], [10]), Tunç ([15], [17], [18]), C. Tunç and E. [16], Zhernovyi and Kostenko [20] and the papers mentioned above. It should be noted that in spite of the equation considered in [18] and (1.1) are the same as one another, the conditions established here and the method of proof partially different than that in [18].

2. The main result

The following result is established.

Theorem: In addition to the basic assumptions imposed on the functions $b, \dots, e, f_1, \dots, f_5$, and p , suppose that the following conditions are satisfied ($\alpha_1, \dots, \alpha_5$ —some arbitrary positive constants and $\varepsilon, \varepsilon_0, \varepsilon_1, \dots, \varepsilon_5$ are some sufficiently small positive constants):

(i) $B \geq b(t) \geq b_0 \geq 1, C \geq c(t) \geq c_0 \geq 1, D \geq d(t) \geq d_0 \geq 1, E \geq e(t) \geq e_0 \geq 1$ for all $t \in R^+$ (here $B, C, D, E, b_0, c_0, d_0$ and e_0 are some constants).

(ii)

$$\alpha_1 > 0, \alpha_1\alpha_2 - \alpha_3 > 0, (\alpha_1\alpha_2 - \alpha_3)\alpha_3 - (\alpha_1\alpha_4 - \alpha_5)\alpha_1 > 0, \quad (2.1)$$

$$\delta_0 := \alpha_1 > 0, (\alpha_3\alpha_4 - \alpha_2\alpha_5)(\alpha_1\alpha_2 - \alpha_3) - (\alpha_1\alpha_4 - \alpha_5)^2 > 0, \alpha_5 > 0, \quad (2.2)$$

$$\Delta_1 := \frac{(\alpha_3\alpha_4 - \alpha_2\alpha_5)(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} - \left[\alpha_1 d(t) \frac{\partial}{\partial y} f_4(x, y) - \alpha_5 \right] \geq 2\varepsilon\alpha_2 \quad (2.3)$$

for all $t \in R^+$ and all x and y ,

$$\Delta_2 := \frac{\alpha_3\alpha_4 - \alpha_2\alpha_5}{\alpha_1\alpha_4 - \alpha_5} - \frac{(\alpha_1\alpha_4 - \alpha_5) \cdot \gamma \cdot d(t)}{\alpha_4(\alpha_1\alpha_2 - \alpha_5)} - \frac{\varepsilon}{\alpha_1} > 0 \quad (2.4)$$

for all $t \in R^+$ and all x and y , where

$$\gamma := \begin{cases} \frac{f_4(x, y)}{y}, & y \neq 0 \\ \frac{\partial}{\partial y} f_4(x, 0), & y = 0. \end{cases} \quad (2.5)$$

(iii) $\varepsilon_0 \leq f_1(t, x, y, z, w, u) - \alpha_1 \leq \varepsilon_1$ for all $t \in R^+$ and all x, y, z, w and u .

(iv)

$$f_2(x, y, z, 0) = 0, 0 \leq \frac{f_2(x, y, z, w)}{w} - \alpha_2 \leq \varepsilon_2 \text{ for all } x, y, z \text{ and } w \neq 0, \quad (2.6)$$

$$yw \frac{\partial}{\partial x} f_2(x, y, z, w) \leq 0, zw \frac{\partial}{\partial y} f_2(x, y, z, w) \leq 0 \text{ and } \frac{\partial}{\partial z} f_2(x, y, z, w) \leq 0 \quad (2.7)$$

for all x, y, z and w .

(v)

$$f_3(x, y, 0) = 0, 0 \leq \frac{f_3(x, y, z)}{z} - \alpha_3 \leq \varepsilon_3 \text{ for all } x, y \text{ and } z \neq 0, \quad (2.8)$$

$$yz \frac{\partial}{\partial x} f_3(x, y, z) \leq 0 \text{ and } \frac{\partial}{\partial y} f_3(x, y, z) \leq 0 \text{ for all } x, y \text{ and } z. \quad (2.9)$$

(vi)

$$f_4(x, 0) = 0, \frac{f_4(x, y)}{y} \geq \frac{E\alpha_4}{d_0} \text{ for all } x \text{ and } y \neq 0, \quad (2.10)$$

$$\left| \alpha_4 - \frac{\partial}{\partial y} f_4(x, y) \right| \leq \varepsilon_4 \text{ for all } x \text{ and } y, \quad (2.11)$$

$$\frac{\partial}{\partial y} f_4(x, y) - \frac{f_4(x, y)}{y} \leq \frac{\alpha_5 \delta_0}{D \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} \text{ for all } x \text{ and } y \neq 0, \quad (2.12)$$

$$\left[\frac{\partial}{\partial x} f_4(x, y) \right]^2 \leq \min \left[\frac{\varepsilon^2 \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)}{16D(\alpha_1 \alpha_4 - \alpha_5)}, \frac{\Delta_1 \varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)}{16D \alpha_1^2 (\alpha_1 \alpha_4 - \alpha_5)} \right] \text{ for all } x \text{ and } y, \quad (2.13)$$

and

$$\frac{1}{y} \int_0^y \frac{\partial}{\partial x} f_4(x, \eta) d\eta \leq -\frac{\varepsilon \alpha_4}{2} \text{ for all } x \text{ and } y \neq 0. \quad (2.14)$$

(vii)

$$f_5(0) = 0, f_5(x) \operatorname{sgn} x > 0 \ (x \neq 0), F_5(x) = \int_0^x f_5(\xi) d\xi \rightarrow \infty \text{ as } |x| \rightarrow \infty, \quad (2.15)$$

and

$$0 \leq \alpha_5 - f_5'(x) \leq \varepsilon_5 \text{ for all } x. \quad (2.16)$$

(viii)

$$\int_0^\infty \beta_0(t) dt < \infty, e'(t) \rightarrow 0 \text{ as } t \rightarrow \infty,$$

where

$$\beta_0(t) := b_+(t) + c_+'(t) + |d'(t)| + |e'(t)|,$$

$$b_+(t) = \max \{b'(t), 0\}, c_+'(t) := \max \{c'(t), 0\}.$$

(ix) $|p(t, x, y, z, w, u)| \leq p_1(t) + p_2(t) [F_5(x) + y^2 + z^2 + w^2 + u^2]^{\frac{\sigma}{2}} + \Delta (y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}}$, where σ, Δ are constants such that $0 \leq \sigma \leq 1, \Delta \geq 0$ (is sufficiently small), and p_1, p_2 are non-negative continuous functions satisfying

$$\int_0^\infty p_i(t) dt < \infty \ (i = 1, 2).$$

Then all solution $x(t)$ of (1.1) is uniformly bounded and satisfies

$$x(t), \dot{x}(t), \ddot{x}(t), \dddot{x}(t), x^{(4)}(t) \rightarrow 0 \text{ as } t \rightarrow \infty.$$

Remark 1: It should be pointed out that in the special case where $f_1(t, x, y, z, w, u) = \alpha_1$, $b(t)f_2(x, y, z, w) = \alpha_2 w$, $c(t)f_3(x, y, z) = \alpha_3 z$, $d(t)f_4(x, y) = \alpha_4 y$, $e(t)f_5(x) =$

$\alpha_5 x$ and $p(t, x, y, z, w, u) = 0$ in the equation (1.1) (so that all the assumptions (ii)-(vii) of the theorem are automatically fulfilled), the equation (1.1) reduces to the linear constant coefficient differential equation and the assumptions (ii)-(vii) of the theorem reduce to the corresponding Routh-Hurwitz criterion.

Remark 2: It should be noted that the theorem stated just above includes the results in ([2], [3]) and [15] and improves the results in ([2], [3]); because the equation (1.1) is more general than those considered there and the result stated here can be proved without the restriction $A \geq a(t) \geq a_0 \geq 1$ in ([2], [3]).

3. The Lyapunov Function $V_0(t, x, y, z, w, u)$

Our main tool in the proof of the theorem is the function $V_0 = V_0(t, x, y, z, w, u)$ defined as follows:

$$\begin{aligned}
2V_0 = & u^2 + 2\alpha_1 uw + \frac{2\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} uz + 2\delta uy + 2b(t) \int_0^w f_2(x, y, z, \rho) d\rho + \left[\alpha_1^2 - \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{(\alpha_1\alpha_4 - \alpha_5)} \right] w^2 \\
& + 2 \left[\alpha_3 + \frac{\alpha_1\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} - \delta \right] wz + 2\alpha_1\delta w + 2d(t)wf_4(x, y) + 2e(t)wf_5(x) \\
& + 2\alpha_1c(t) \int_0^z f_3(x, y, \zeta) d\zeta + \left[\frac{2\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} - \alpha_4 - \alpha_1\delta \right] z^2 + 2\delta\alpha_2yz + 2\alpha_1d(t)zf_4(x, y) \\
& - 2\alpha_5zy + 2\alpha_1e(t)zf_5(x) + \frac{2\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} d(t) \int_0^y f_4(x, \eta) d\eta + (\delta\alpha_3 - \alpha_1\alpha_5)y^2 \\
& + \frac{2\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} e(t)yf_5(x) + 2\delta e(t) \int_0^x f_5(\xi) d\xi + k,
\end{aligned} \tag{3.1}$$

where δ is a positive constant satisfying

$$\delta := \frac{\alpha_5(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} + \varepsilon, \tag{3.2}$$

and k is a positive constant to be determined later in the proof.

In order to prove the theorem we need the following two lemmas.

Lemma 1: Subject to the conditions (i) - (vii) of the theorem, there exist positive constants D_7 and D_8 such that

$$D_7 [F_5(x) + y^2 + z^2 + w^2 + u^2 + k] \leq V_0 \leq D_8 [F_5(x) + y^2 + z^2 + w^2 + u^2 + k]. \tag{3.3}$$

Proof: The function $V_0 = V_0(t, x, y, z, w, u)$ defined in (3.1) can be arranged as follows:

$$\begin{aligned}
2V_0 = & \left[u + \alpha_1 w + \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} z + \delta y \right]^2 + \frac{\alpha_4\delta_0}{(\alpha_1\alpha_4 - \alpha_5)^2} \left(z + \frac{\alpha_5}{\alpha_4} y \right)^2 + \Delta_2(w + \alpha_1 z)^2 \\
& + \frac{\alpha_4(\alpha_1\alpha_4 - \alpha_5)}{(\alpha_1\alpha_2 - \alpha_3)\gamma \cdot d(t)} \left[\frac{(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} e(t) f_5(x) + \frac{(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} \gamma \cdot d(t) y + \frac{\alpha_1}{\alpha_4} \gamma \cdot d(t) z + \frac{1}{\alpha_4} \gamma \cdot d(t) w \right]^2 \\
& + 2\varepsilon \left(\frac{\alpha_3\alpha_4 - \alpha_2\alpha_5}{\alpha_1\alpha_4 - \alpha_5} \right) yz + k + \sum_{i=1}^4 V_i,
\end{aligned} \tag{3.4}$$

where

$$V_1 := 2\delta e(t) \int_0^x f_5(\xi) d\xi - \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{(\alpha_1\alpha_4 - \alpha_5)\gamma \cdot d(t)} e^2(t) f_5^2(x),$$

$$\begin{aligned}
V_2 := & \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)d(t)}{\alpha_1\alpha_4 - \alpha_5} \left[2 \int_0^y f_4(x, \eta) d\eta - y f_4(x, y) \right] \\
& + \left[\delta\alpha_3 - \alpha_1\alpha_5 - \frac{\alpha_5^2\delta_0}{\alpha_4(\alpha_1\alpha_4 - \alpha_5)^2} - \delta^2 \right] y^2,
\end{aligned}$$

$$V_3 := \frac{\varepsilon}{\alpha_1} w^2 + 2b(t) \int_0^w f_2(x, y, z, \rho) d\rho - \alpha_2 w^2,$$

$$V_4 := 2\alpha_1 c(t) \int_0^z f_3(x, y, \zeta) d\zeta - \alpha_1\alpha_3 z^2.$$

Now, the function V_1 here can be estimated as in [15]. In fact the estimates there show that

$$V_1 \geq 2\varepsilon e_0 \int_0^x f_5(\xi) d\xi.$$

Since

$$y f_4(x, y) \equiv \int_0^y f_4(x, \eta) d\eta + \int_0^y \eta \frac{\partial}{\partial \eta} f_4(x, \eta) d\eta,$$

then, by using (i) and (vi), we obtain

$$\begin{aligned}
V_2 &= \frac{\alpha_4(\alpha_1\alpha_2-\alpha_3)d(t)}{\alpha_1\alpha_4-\alpha_5} \left[2 \int_0^y f_4(x, \eta) d\eta - y f_4(x, y) \right] + \left[\frac{\alpha_5\delta_0}{\alpha_4(\alpha_1\alpha_4-\alpha_5)} - \varepsilon \left(\varepsilon + \frac{2\alpha_5(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} - \alpha_3 \right) \right] y^2 \\
&= \int_0^y \left[\frac{2\alpha_5\delta_0}{\alpha_4(\alpha_1\alpha_4-\alpha_5)} - \frac{\alpha_4(\alpha_1\alpha_2-\alpha_3)d(t)}{\alpha_1\alpha_4-\alpha_5} \left\{ \frac{\partial}{\partial \eta} f_4(x, \eta) - \frac{f_4(x, \eta)}{\eta} \right\} - 2\varepsilon \left\{ \varepsilon + \frac{2\alpha_5(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} - \alpha_3 \right\} \right] \eta d\eta \\
&\geq \int_0^y \left[\frac{\alpha_5\delta_0}{\alpha_4(\alpha_1\alpha_4-\alpha_5)} - 2\varepsilon \left\{ \varepsilon + \frac{2\alpha_5(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} - \alpha_3 \right\} \right] \eta d\eta \geq \frac{\alpha_5\delta_0}{4\alpha_4(\alpha_1\alpha_4-\alpha_5)} y^2
\end{aligned}$$

provided that

$$\frac{\alpha_5\delta_0}{4\alpha_4(\alpha_1\alpha_4-\alpha_5)} \geq \varepsilon \left[\varepsilon + \frac{2\alpha_5(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} - \alpha_3 \right]$$

which we now assume

In view of assumptions(i) and (iv) of the theorem, it follows that

$$V_3 \geq \frac{\varepsilon}{\alpha_1} w^2 + 2 \int_0^w \left[\frac{f_2(x, y, z, \rho)}{\rho} - \alpha_3 \right] \rho d\rho \geq \frac{\varepsilon}{\alpha_1} w^2.$$

Similarly, from (v) $V_4 = 0$ when $z = 0$, and again from (i) and (v) if $z \neq 0$

$$V_4 \geq 2\alpha_1 \int_0^z \left[\frac{f_3(x, y, \zeta)}{\zeta} - \alpha_3 \right] \zeta d\zeta \geq 0.$$

Therefore V_4 satisfies $V_4 \geq 0$ for all x, y and z .

Now, making the use of the estimates for V_1, V_2, V_3 and V_4 with (34), we have that

$$\begin{aligned}
2V_0 &\geq \left[u + \alpha_1 w + \frac{\alpha_4(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} z + \delta y \right]^2 + \frac{\alpha_4\delta_0}{(\alpha_1\alpha_4-\alpha_5)^2} \left(z + \frac{\alpha_5}{\alpha_4} y \right)^2 + \Delta_2(w + \alpha_1 z)^2 \\
&\quad + 2\varepsilon e_0 \int_0^x f_5(\xi) d\xi + \frac{\alpha_5\delta_0}{4\alpha_4(\alpha_1\alpha_4-\alpha_5)} y^2 + \frac{\varepsilon}{\alpha_1} w^2 + 2\varepsilon \left(\frac{\alpha_3\alpha_4-\alpha_2\alpha_5}{\alpha_1\alpha_4-\alpha_5} \right) yz + k.
\end{aligned}$$

The remainder of the proof exists in [15] and hence is omitted.

Lemma 2: Suppose that all the conditions of the theorem are satisfied. Then there exist positive constants D_i ($i = 11, 12, 13$) such that

$$\begin{aligned}
\dot{V}_0 &\leq -D_{13} [y^2 + z^2 + w^2 + u^2] + 2D_{12} (y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} [p_1(t) + p_2(t)] \\
&\quad + 2D_{12} p_2(t) [F_5(x) + y^2 + z^2 + w^2 + u^2] + D_{11} \beta_0 V_0.
\end{aligned} \tag{3.5}$$

Proof: Along any solution (x, y, z, w, u) of (1.2) it follows from (3.1) and (1.2) that (for $y, z, w \neq 0$)

$$\begin{aligned}
\dot{V}_0 = & -u^2[f_1(t, x, y, z, w, u) - \alpha_1] - w^2 \left[\alpha_1 \frac{b(t)f_2(x, y, z, w)}{w} - \left\{ \alpha_3 + \frac{\alpha_1\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} - \delta \right\} \right] \\
& - z^2 \left[\frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} \frac{c(t)f_3(x, y, z)}{z} - \left\{ \delta\alpha_2 + \alpha_1 d(t) \frac{\partial}{\partial y} f_4(x, y) - \alpha_5 \right\} \right] \\
& - y^2 \left[\delta d(t) \frac{f_4(x, y)}{y} - \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} e(t) f_5'(x) \right] - \alpha_1 u w [f_1(t, x, y, z, w, u) - \alpha_1] \\
& - u z c(t) \left[\frac{f_3(x, y, z)}{z} - \alpha_3 \right] - \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} u z [f_1(t, x, y, z, w, u) - \alpha_1] \\
& - \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} w z b(t) \left[\frac{f_2(x, y, z, w)}{w} - \alpha_2 \right] - \delta u y [f_1(t, x, y, z, w, u) - \alpha_1] \\
& - w y e(t) [\alpha_5 - f_5'(x)] - \delta w y b(t) \left[\frac{f_2(x, y, z, w)}{w} - \alpha_2 \right] - \alpha_1 z y e(t) [\alpha_5 - f_5'(x)] \\
& - \delta z y c(t) \left[\frac{f_3(x, y, z)}{z} - \alpha_3 \right] - w z d(t) \left[\alpha_4 - \frac{\partial}{\partial y} f_4(x, y) \right] + d(t) w y \frac{\partial}{\partial x} f_4(x, y) \\
& + b(t) y \int_0^w \frac{\partial}{\partial x} f_2(x, y, z, \rho) d\rho + b(t) z \int_0^w \frac{\partial}{\partial y} f_2(x, y, z, \rho) d\rho + b(t) w \int_0^w \frac{\partial}{\partial z} f_2(x, y, z, \rho) d\rho \\
& + \alpha_1 c(t) y \int_0^z \frac{\partial}{\partial x} f_3(x, y, \zeta) d\zeta + \alpha_1 c(t) z \int_0^z \frac{\partial}{\partial y} f_3(x, y, \zeta) d\zeta + \alpha_1 d(t) z y \frac{\partial}{\partial x} f_4(x, y) \\
& + \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} d(t) y \int_0^y \frac{\partial}{\partial x} f_4(x, \eta) d\eta + \left[\frac{\alpha_2\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} z w + \delta\alpha_2 y w \right] [1 - b(t)] \\
& + [\alpha_3 z u + \delta\alpha_3 y z] [1 - c(t)] - \alpha_4 w z [1 - d(t)] - [\alpha_5 y w + \alpha_1\alpha_5 y z] [1 - e(t)] \\
& + \left[u + \alpha_1 w + \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} z + \delta y \right] \cdot p(t, x, y, z, w, u) + \frac{\partial V_0}{\partial t}.
\end{aligned} \tag{3.6}$$

The assumption (iii) of the theorem shows that

$$[f_1(t, x, y, z, w, u) - \alpha_1] \geq \varepsilon_0. \tag{3.7}$$

It follows from (i), (ii), (iv) and (3.2) that (for $w \neq 0$)

$$\begin{aligned}
& \alpha_1 \frac{b(t)f_2(x, y, z, w)}{w} - \left\{ \alpha_3 + \frac{\alpha_1\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} - \delta \right\} \\
& \geq \alpha_1 \left[\frac{f_2(x, y, z, w)}{w} - \alpha_2 \right] + \left[\alpha_1\alpha_2 - \alpha_3 + \delta - \frac{\alpha_1\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} \right] \geq \varepsilon.
\end{aligned} \tag{3.8}$$

By using (i), (ii), (v) and (3.2) we have that (for $z \neq 0$)

$$\begin{aligned}
& \frac{\alpha_4(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} \frac{c(t)f_3(x,y,z)}{z} - \left[\delta\alpha_2 + \alpha_1 d(t) \frac{\partial}{\partial y} f_4(x,y) - \alpha_5 \right] \\
& \geq \frac{\alpha_3\alpha_4(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} - \left[\delta\alpha_2 + \alpha_1 d(t) \frac{\partial}{\partial y} f_4(x,y) - \alpha_5 \right] \\
& = \frac{(\alpha_1\alpha_2-\alpha_3)(\alpha_3\alpha_4-\alpha_2\alpha_5)}{\alpha_1\alpha_4-\alpha_5} - \left[\alpha_1 d(t) \frac{\partial}{\partial y} f_4(x,y) - \alpha_5 \right] - \varepsilon\alpha_2 > (\varepsilon\alpha_2).
\end{aligned} \tag{3.9}$$

By noting the assumptions (i), (vi), (vii) of the theorem, (2.10) and (3.2) we obtain that (for $y \neq 0$)

$$\begin{aligned}
\delta d(t) \frac{f_4(x,y)}{y} - \frac{\alpha_4(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} e(t) f_5'(x) & \geq \delta E\alpha_4 - \frac{\alpha_4(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} E f_5'(x) \\
& = \varepsilon E\alpha_4 + \frac{\alpha_4 E(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} [\alpha_5 - f_5'(x)] \\
& \geq \varepsilon\alpha_4 E.
\end{aligned} \tag{3.10}$$

Hence the first four terms, involving u^2, w^2, z^2 and y^2 in (3.6), are majorizable by

$$-(\varepsilon_0 u^2 + \varepsilon w^2 + \varepsilon\alpha_2 z^2 + \varepsilon\alpha_4 E y^2).$$

It is also clear that

$$\begin{aligned}
y \int_0^z \frac{\partial}{\partial x} f_3(x,y,\zeta) d\zeta \leq 0, z \int_0^z \frac{\partial}{\partial y} f_3(x,y,\zeta) d\zeta \leq 0, y \int_0^w \frac{\partial}{\partial x} f_2(x,y,z,\rho) d\rho \leq 0, \\
z \int_0^w \frac{\partial}{\partial y} f_2(x,y,z,\rho) d\rho \leq 0, w \int_0^w \frac{\partial}{\partial z} f_2(x,y,z,\rho) d\rho \leq 0 \text{ by (2.7) and (2.9)}.
\end{aligned} \tag{3.11}$$

Now consider the terms

$$V_6 = d(t) \left[wy \frac{\partial}{\partial x} f_4(x,y) + \alpha_1 zy \frac{\partial}{\partial x} f_4(x,y) \right] + \frac{d(t)\alpha_4(\alpha_1\alpha_2-\alpha_3)}{\alpha_1\alpha_4-\alpha_5} y^2 \left[\frac{1}{y} \int_0^y \frac{\partial}{\partial x} f_4(x,\eta) d\eta \right],$$

which are contained in (3.6).

$$\begin{aligned}
-V_6 &\geq -d(t) \left[wy \frac{\partial}{\partial x} f_4(x, y) + \alpha_1 zy \frac{\partial}{\partial x} f_4(x, y) \right] + \frac{d(t)\alpha_4^2 \varepsilon (\alpha_1 \alpha_2 - \alpha_3)}{2(\alpha_1 \alpha_4 - \alpha_5)} y^2 \\
&= \frac{d(t)\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)}{4(\alpha_1 \alpha_4 - \alpha_5)} \left[y^2 - \frac{4(\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} y w \frac{\partial}{\partial x} f_4(x, y) \right] \\
&\quad + \frac{d(t)\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)}{4(\alpha_1 \alpha_4 - \alpha_5)} \left[y^2 - \frac{4\alpha_1 (\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} y z \frac{\partial}{\partial x} f_4(x, y) \right] \\
&= \frac{d(t)\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)}{4(\alpha_1 \alpha_4 - \alpha_5)} \left[y - \frac{2(\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} w \frac{\partial}{\partial x} f_4(x, y) \right]^2 - \frac{d(t)(\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} w^2 \left[\frac{\partial}{\partial x} f_4(x, y) \right]^2 \\
&\quad + \frac{d(t)\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)}{4(\alpha_1 \alpha_4 - \alpha_5)} \left[y - \frac{2\alpha_1 (\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} z \frac{\partial}{\partial x} f_4(x, y) \right]^2 - \frac{d(t)\alpha_1^2 (\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} z^2 \left[\frac{\partial}{\partial x} f_4(x, y) \right]^2 \\
&\geq -\frac{D(\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} w^2 \left[\frac{\partial}{\partial x} f_4(x, y) \right]^2 - \frac{D\alpha_1^2 (\alpha_1 \alpha_4 - \alpha_5)}{\varepsilon \alpha_4^2 (\alpha_1 \alpha_2 - \alpha_3)} z^2 \left[\frac{\partial}{\partial x} f_4(x, y) \right]^2 \\
&\geq -\left(\frac{\varepsilon}{16}\right) w^2 - \left(\frac{\varepsilon \alpha_2}{16}\right) z^2,
\end{aligned}$$

by (i), (ii), (2.13) and (2.14).

Hence

$$V_6 \leq \left(\frac{\varepsilon}{16}\right) w^2 + \left(\frac{\varepsilon \alpha_2}{16}\right) z^2. \quad (3.12)$$

Now, let $R(t, x, y, z, w, u)$ denote the sum of the remaining terms in (3.6). Following the procedure indicated in [15], one can conclude that

$$\begin{aligned}
|R(t, x, y, z, w, u)| &\leq D_9(\varepsilon_1 + \varepsilon_2 + \varepsilon_3 + \varepsilon_4 + \varepsilon_5)(y^2 + z^2 + w^2 + u^2) \\
&\quad + \left| u + \alpha_1 w + \frac{\alpha_4(\alpha_1 \alpha_2 - \alpha_3)}{\alpha_1 \alpha_4 - \alpha_5} z + \delta y \right| \cdot |p(t, x, y, z, w, u)| + \frac{\partial V_0}{\partial t}
\end{aligned} \quad (3.13)$$

for a constant $D_9 > 0$.

On substituting the estimates (3.7)-(3.13) in (3.6) we find

$$\begin{aligned}
\dot{V}_0 &\leq -\varepsilon_0 u^2 - \left(\frac{15\varepsilon}{16}\right) w^2 - \left(\frac{15\varepsilon \alpha_2}{16}\right) z^2 - (\varepsilon \alpha_4 E) y^2 \\
&\quad + D_9(\varepsilon_1 + \varepsilon_2 + \varepsilon_3 + \varepsilon_4 + \varepsilon_5)(y^2 + z^2 + w^2 + u^2) \\
&\quad + \left| u + \alpha_1 w + \frac{\alpha_4(\alpha_1 \alpha_2 - \alpha_3)}{\alpha_1 \alpha_4 - \alpha_5} z + \delta y \right| \cdot |p(t, x, y, z, w, u)| + \frac{\partial V_0}{\partial t} \\
&\leq -\frac{1}{2} \min \left\{ \varepsilon_0, \frac{15\varepsilon}{16}, \frac{15\varepsilon \alpha_2}{16}, \varepsilon \alpha_4 E \right\} (y^2 + z^2 + w^2 + u^2) \\
&\quad + \left| u + \alpha_1 w + \frac{\alpha_4(\alpha_1 \alpha_2 - \alpha_3)}{\alpha_1 \alpha_4 - \alpha_5} z + \delta y \right| \cdot |p(t, x, y, z, w, u)| + \frac{\partial V_0}{\partial t}
\end{aligned}$$

provided that

$$D_9(\varepsilon_1 + \varepsilon_2 + \varepsilon_3 + \varepsilon_4 + \varepsilon_5) \leq \frac{1}{2} \min \left\{ \varepsilon_0, \frac{15\varepsilon}{16}, \frac{15\varepsilon\alpha_2}{16}, \varepsilon\alpha_4 E \right\}. \quad (3.14)$$

Now we assume that D_9 and $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_5$ are so small that (3.14) holds. The case $y, z, w = 0$ is obvious. From (3.1) we get

$$\begin{aligned} \frac{\partial V_0}{\partial t} = & e'(t) \left[w f_5(x) + \alpha_1 z f_5(x) + \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} y f_5(x) + \delta \int_0^x f_5(\xi) d\xi \right] \\ & + d'(t) \left[w f_4(x, y) + \alpha_1 z f_4(x, y) + \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} \int_0^y f_4(x, \eta) d\eta \right] \\ & + \alpha_1 c'(t) \int_0^z f_3(x, y, \zeta) d\zeta + b'(t) \int_0^w f_2(x, y, z, \rho) d\rho. \end{aligned}$$

The relation (3.3) and assumptions (iv)-(vii) of the theorem show that

$$\frac{\partial V_0}{\partial t} \leq D_{10} [b'_+(t) + c'_+(t) + |d'(t)| + |e'(t)|] [F_5(x) + y^2 + z^2 + w^2 + u^2] \leq D_{11}\beta_0 V_0, \quad (3.15)$$

where D_{10} is a positive constant and $D_{11} = \frac{D_{10}}{D_7}$.

Let

$$D_{13} = \frac{1}{2} \min \left\{ \varepsilon_0, \frac{15\varepsilon}{16}, \frac{15\varepsilon\alpha_2}{16}, \varepsilon\alpha_4 E \right\} \quad \text{and} \quad D_{12} = \max \left\{ 1, \alpha_1, \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_4}, \delta \right\}.$$

Using the Cauchy inequality and the assumption (ix) of the theorem we obtain

$$\begin{aligned} \dot{V}_0 & \leq -2D_{13}(y^2 + z^2 + w^2 + u^2) + \left| u + \alpha_1 w + \frac{\alpha_4(\alpha_1\alpha_2 - \alpha_3)}{\alpha_1\alpha_4 - \alpha_5} z + \delta y \right| \cdot |p(t, x, y, z, w, u)| + D_{11}\beta_0 V_0 \\ & \leq -2D_{13}(y^2 + z^2 + w^2 + u^2) + 2D_{12}(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} \cdot |p(t, x, y, z, w, u)| + D_{11}\beta_0 V_0 \\ & \leq -2D_{13}(y^2 + z^2 + w^2 + u^2) + 2D_{12}(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} \\ & \quad \times \left[p_1(t) + p_2(t) \{F_5(x) + y^2 + z^2 + w^2 + u^2\}^{\frac{\sigma}{2}} + \Delta(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} \right] \\ & \quad + D_{11}\beta_0 V_0. \end{aligned} \quad (3.16)$$

It is obvious from (3.15) and (3.16) that

$$\begin{aligned} \dot{V}_0 & \leq -2D_{13}(y^2 + z^2 + w^2 + u^2) + 2D_{12}(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} \\ & \quad \times \left[p_1(t) + p_2(t) \{F_5(x) + y^2 + z^2 + w^2 + u^2\}^{\frac{\sigma}{2}} + \Delta(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} \right] + D_{11}\beta_0 V_0. \end{aligned}$$

Let's fix Δ in what follows, to satisfy $\Delta = \frac{D_{13}}{2D_{12}}$. By this limitation on Δ , we obtain

$$\begin{aligned} \dot{V}_0 &\leq -D_{13}(y^2 + z^2 + w^2 + u^2) + 2D_{12}(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} \\ &\quad \times \left[p_1(t) + p_2(t) \{F_5(x) + y^2 + z^2 + w^2 + u^2\}^{\frac{\sigma}{2}} \right] + D_{11}\beta_0 V_0. \end{aligned}$$

Using the inequality

$$[F_5(x) + y^2 + z^2 + w^2 + u^2]^{\frac{\sigma}{2}} \leq 1 + [F_5(x) + y^2 + z^2 + w^2 + u^2]^{\frac{1}{2}}$$

we find

$$\begin{aligned} \dot{V}_0 &\leq -D_{13}(y^2 + z^2 + w^2 + u^2) + 2D_{12}(y^2 + z^2 + w^2 + u^2)^{\frac{1}{2}} [p_1(t) + p_2(t)] \\ &\quad + 2D_{12}p_2(t) [F_5(x) + y^2 + z^2 + w^2 + u^2] + D_{11}\beta_0 V_0. \end{aligned}$$

This completes the proof of the lemma.

4. Completion of the proof of the theorem

The completion proof of the theorem is similar to that of the theorem established in [15] and hence it is omitted.

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